

Table of contents

Emília BUBENÍKOVÁ, Alžbeta KANALÍKOVÁ, Marián HRUBOŠ Control of Mobile Robot Using Web Interface DOI: 10.22223/tr.2016-2/2013	1
Karel FRYDRÝŠEK Simple Statically Indeterminate Truss (Linear, Nonlinear and Stochastic Approach) DOI: 10.22223/tr.2016-2/2014	7
Stefan GRUSHKO, Zdenko BOBOVSKÝ Teleoperated Humanoid Robot DOI: 10.22223/tr.2016-2/2015	21
Jaroslav HRICKO, Štefan HAVLÍK Stiffness Models of Novel Force/Displacement Sensors DOI: 10.22223/tr.2016-2/2016	29
Marián HRUBOŠ, Dušan NEMEC, Vojtech ŠIMÁK, Jozef HRBČEK, Rastislav PIRNÍK Measurement of 3D Space Using a 2D Profilograph DOI: 10.22223/tr.2016-2/2017	37
Vladislav OCHODEK, Stanislav RUSZ Residual Stresses Analysis Methodology During Cyclic Plastic Deformation Carbon Steel DOI: 10.22223/tr.2016-2/2018	43
Jiří SUDER, Zdenko BOBOVSKÝ, Václav KRYS, Tomáš KOT Modifications of the Mobile Robotic System Crawler DOI: 10.22223/tr.2016-2/2019	49
Ján VACHÁLEK, Oliver ROVNÝ, Rudolf PALENČÁR, Stanislav ĎURIŠ Measuring Distances Using the 3D Optical Device for the Needs of Mobile Robotics DOI: 10.22223/tr.2016-2/2020	61
Karol VASILKO, Jozef PILC, Dana STANČEKOVÁ, Robert ČEP Development and Applications of a Free Cutting by Nonconventional Tools DOI: 10.22223/tr.2016-2/2021	77